$I_0(4t) = 0.99999 99985 + 4.00000 01935 t^2 + 3.99999 59541 t^4$ + 1.77780 99690 t^{6} + 0.44431 89384 t^{8} + 0.07137 58187 t^{10} + 0.00759 42968 t^{12} + 0.00082 67816 t^{14} (17 × 10⁻¹⁰), $t^{-1}I_1(4t) = 1.99999 \ 99997 + 4.00000 \ 00421 \ t^2 + 2.66666 \ 57853 \ t^4$ + 0.88889 59049 t^6 + 0.17775 04042 t^8 + 0.02376 15011 t^{10} $+ 0.00219 \ 0.00219 \ t^{12} + 0.00020 \ 11611 \ t^{14} \ (4 \times 10^{-10}),$ $(2\pi)^{-1/2}F_0(4/t) = 0.39894 \ 22809 + 0.01246 \ 67783 \ t + 0.00176 \ 23668 \ t^2$ + 0.00026 22220 t^3 + 0.00225 85672 t^4 - 0.01283 14822 t^5 $+ 0.04958 11198 t^{6} - 0.12099 40805 t^{7} + 0.18954 76618 t^{8}$ $-0.18677 83276 t^{9} + 0.11133 15511 t^{10} - 0.03666 94167 t^{11}$ $+ 0.00512 \ 46015 \ t^{12} \ (7 \times 10^{-10}),$ $(2\pi)^{-1/2}F_1(4/t) = 0.39894 \ 22799 \ - \ 0.03740 \ 06642 \ t \ - \ 0.00293 \ 14981 \ t^2$ - 0.00043 77220 t^{3} - 0.00237 87859 t^{4} + 0.01319 50213 t^{5} -0.05078 72951 t^{6} + 0.12301 43060 t^{7} - 0.19083 32956 t^{8} + 0.18552 23758 t^9 - 0.10862 98349 t^{10} + 0.03497 54315 t^{11} $-0.00474 86397 t^{12} (8 \times 10^{-10}).$

The first two approximations were obtained by the economization method of Lanczos [2], which is used by Hitchcock. As he notes, this method is inapplicable for the last two approximations, and these were obtained by collocation at the zeros of $T_{13}^*(x) = \cos \{13 \cos^{-1} (2x - 1)\}.$

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A. J. M. HITCHCOCK, "Polynomial approximations to Bessel functions of order zero and one and to related functions," *MTAC*, v. 11, 1957, p. 86-88.
C. LANCZOS, *Applied Analysis*, Prentice Hall, Inc., New Jersey, 1956.

A Note on the Curve Fitting of Discrete Data by Economization

By F. D. Burgoyne

Suppose that we are given a set of points $(x_i, y_i) \ 0 \leq i \leq n$ and we desire to find the polynomial p(x) of given degree $m(\langle n)$ such that $\max_i |y_i - p(x_i)|$ is a minimum. It is well known that this may be performed in good approximation by using the method of least squares to find the polynomial q(x) of degree m such that $\sum_{i} \{y_i - q(x_i)\}^2$ is a minimum, and then taking p(x) = q(x) + c, where c is constant given by

 $2c = \min_{i} \{y_i - q(x_i)\} + \max_{i} \{y_i - q(x_i)\}.$

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While several methods (mainly of an iterative nature) exist for finding a better approximation to p(x), e.g., that of Hastings [1], none seem quite so simple as the above. However, the author has for some time also used the following procedure which is both simple and straightforward and does not involve iteration; it is in fact basically the analogue for discrete data of the usual economization process. First, the polynomial of degree n is found which passes exactly through the points (x_i, y_i) , then this polynomial is economized to a polynomial r(x) of degree m over the range $\min_i x_i \leq x \leq \max_i x_i$. We then take p(x) = r(x) + d, where d is a constant given by

$$2d = \min_{i} \{y_{i} - r(x_{i})\} + \max_{i} \{y_{i} - r(x_{i})\}.$$

When n is not too large and the x_i are equally spaced r(x) may be found by hand as follows. First the x_i are transformed so that $x_i = i/n$. Now by Newton's interpolation formula the polynomial of degree n which passes exactly through the points (x_i, y_i) is $\sum_i \binom{nx}{i} \Delta^i x_0$, and the polynomial $r_{nim}(x)$, which $\binom{nx}{i}$ becomes when economized to degree m over the range $0 \leq x \leq 1$, may be found from a previously prepared table. Then $r(x) = \sum_i r_{nim}(x) \Delta^i x_0$. If desired, a different interpolation formula may be used.

In the vast majority of examples tried by the author it was found that

$$\frac{1}{2}\max_i |y_i - q(x_i) - c| \le \max_i |y_i - r(x_i) - d| \le \max_i |y_i - q(x_i) - c|.$$

In each of the few cases in which $\max_i |y_i - r(x_i) - d|$ was greater than $\max_i |y_i - q(x_i) - c|$ it was found that the points (x_i, y_i) gave an inadequate picture of the polynomial of degree n which passed exactly through them; this rarely occurred when the x_i were equally spaced.

For some of the examples p(x) also was found by using Hastings' method [1]. In each of these cases $\max_i |y_i - r(x_i) - d|$ was less than $\frac{5}{4}\max_i |y_i - p(x_i)|$.

As an illustration consider the following example. We are given the points (0, 1), (0.25, 1), (0.5, 15), (0.75, 79), (1, 253), and we desire the quadratic polynomial which best approximates them. In this case p(x) can be found exactly, and we obtain the following results:

$$p(x) = 17 - 244x + 464x^2$$
, maximum error 16;
 $r(x) + d = 15.5 - 228x + 448x^2$, maximum error 17.5.

The maximum error associated with q(x) + c is 19.2.

It may be added that on Pegasus both the least squares and the economization fitting processes take roughly the same time and use roughly the same number of storage locations.

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1. C. HASTINGS, Approximations for Digital Computers, Princeton University Press, 1955.